

**Displacement** from 4 to 31 ccm  
**Pressure** up to 270 bar  
**Speed** from 500 to 4000 RPM

**GEAR MOTORS**  
**TM3**

**TABLE OF CONTENTS**

DESCRIPTION ..... 2

BASIC PARTS OF MOTOR..... 2

PARAMETER TABLE ..... 3

FORMULAS USED FOR CALCULATION ..... 4

PUMP EFFICIENCIES ..... 4

WORKING LIQUID ..... 5

PRESSURE LOAD ..... 5

DIRECTION OF ROTATION ..... 6

REVERSIBLE DESIGN ..... 6

MOTOR WITH A FRONT-END BEARING ..... 6

TM3 FLOW RATE AND POWER CURVES ..... 7

ORDER KEY ..... 10

COMBINATIONS OF FLANGES AND SHAFTS ..... 11

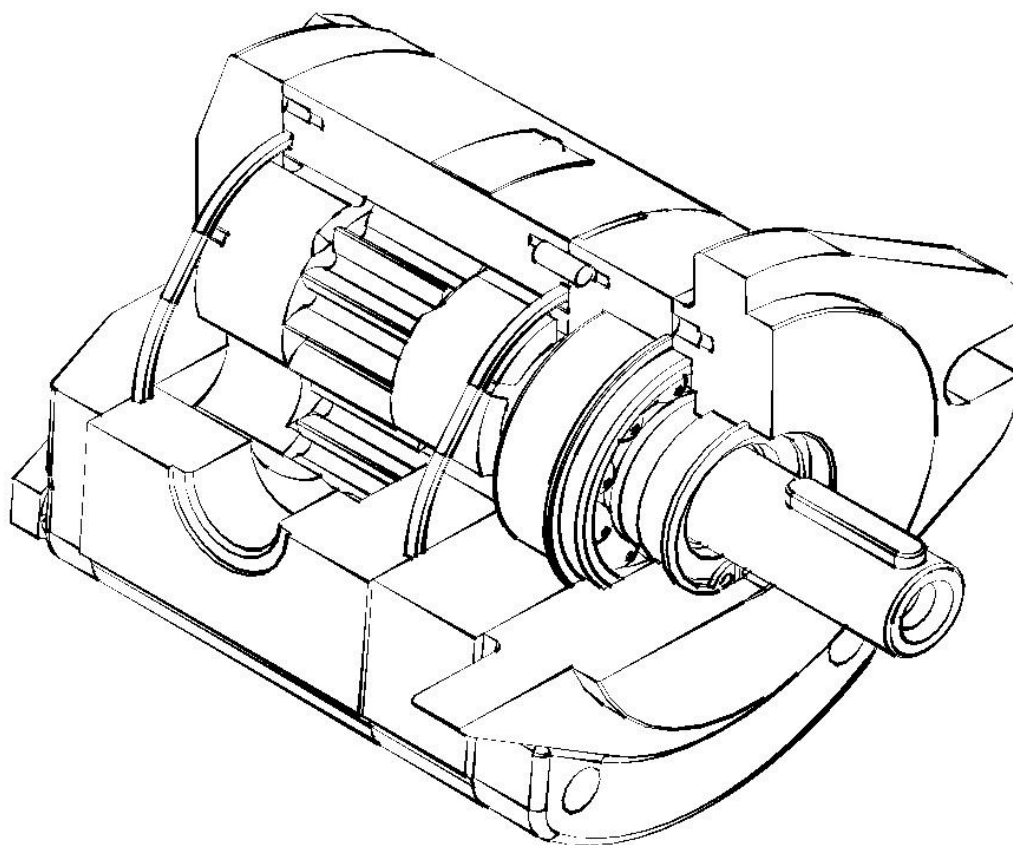
FLANGES DESIGN ..... 12

DRIVE SHAFT ..... 13

LIQUID INLET AND OUTLET CONNECTION ..... 16

CATALOGUE SHEETS OF TM3 SERIES BASIC DESIGNS ..... 17

NOTES:..... 25

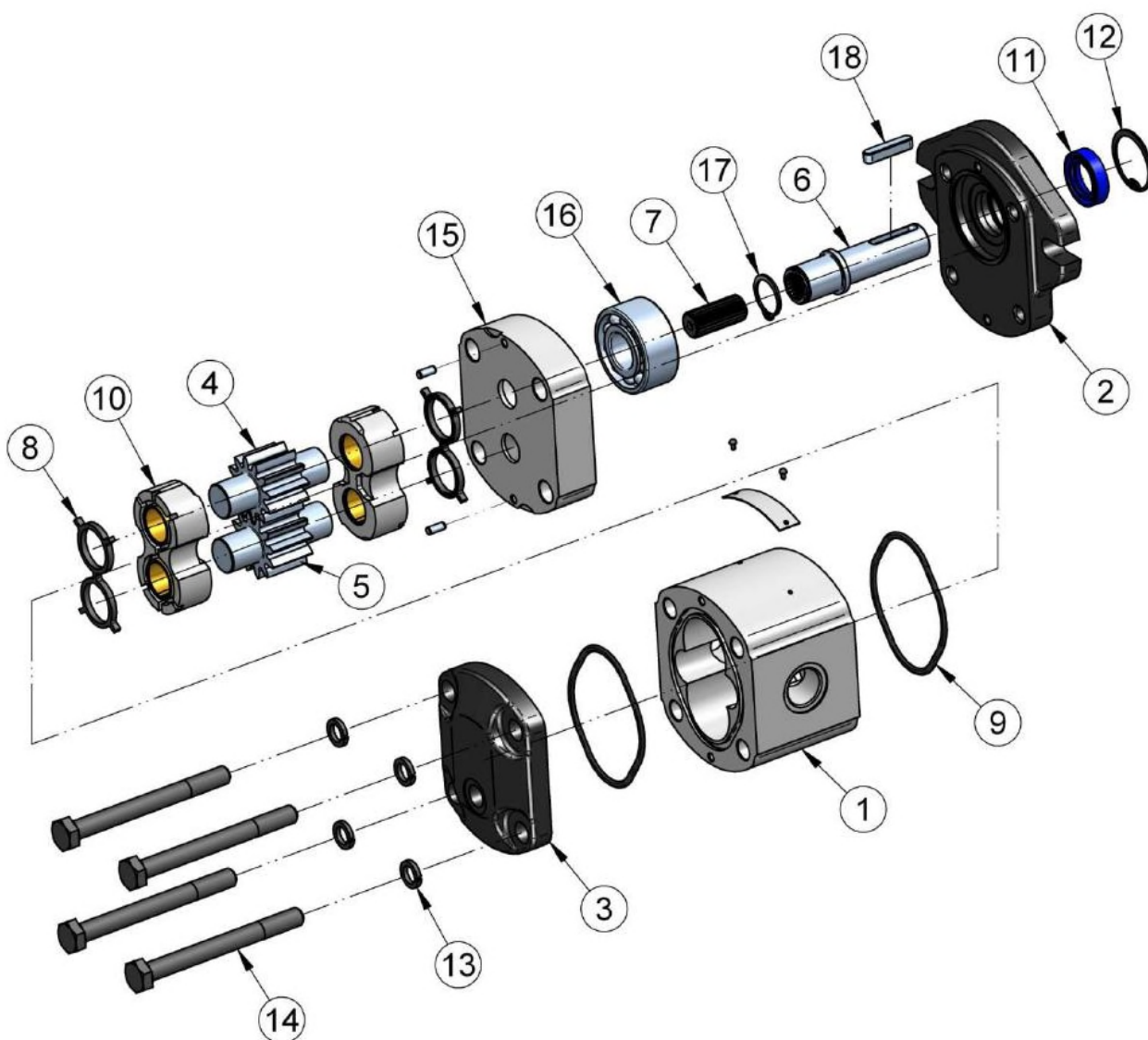


## DESCRIPTION

Gear motors are used for transformation of liquid pressure head in mechanical energy. TM3 series motors with external teeth are due to their simple construction, compact dimensions and a wide range of types applicable in modern hydraulic systems, handling equipment as well as mobile hydraulic systems. Flange types used as well as the form of working liquid inlet and outlet comply with all worldwide standards. The PM23 series covers the range of displacements from 9 to 31 cm<sup>3</sup>/rev.

The basic version consists of several parts. The body is made of a heavy duty aluminium alloy, engine cover and flange of grey iron or eventually aluminium alloy, and gear wheels of heavy duty steel. Axle pins with a high surface duality are imbedded in sliding sleeves, continuously lubricated and cooled by a stream of working liquid. The axial pump balancing is performed using sliding aluminium alloy bearing sleeves in which a shape sealing of balancing surface is located in grooves. TM3 series motors can be delivered in one-way design as clockwise or anti-clockwise rotating engines; they are also available in reversible version.

## BASIC PARTS OF MOTOR



- |                       |                     |
|-----------------------|---------------------|
| 1. Body               | 10. Bearing sleeves |
| 2. Flange             | 11. Shaft seal      |
| 3. Cover              | 12. Safety ring     |
| 4. Driving gear       | 13. Spring washers  |
| 5. Driven gear        | 14. Bolts           |
| 6. Driving shaft      | 15. Body connection |
| 7. Clutch             | 16. Bearing         |
| 8. Balancing sealing  | 17. Safety ring     |
| 9. Peripheral sealing | 18. Key             |

**PARAMETER TABLE**
**One direction motors**

Nominal Size Parameters		Sym	Unit	TM3 4	TM3 6	TM3 8	TM3 12	TM3 16	TM3 20	TM3 25	TM3 31
Actual displacement		$V_g$	[cm <sup>3</sup> ]	4.03	6.02	8.05	12.08	16.10	20.12	25.16	31.21
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500							
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500							
	maximum	$n_{max}$	[min <sup>-1</sup> ]	4000	4000	3600	3600	3200	3200	2800	2200
Pressure at outlet	minimum	$p_{1min}$	[bar]	0.50							
	maximum	$p_{1max}$	[bar]	-0.30							
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	270	270	270	250	250	200	180	150
	maximum	$p_{2max}$	[bar]	290	290	290	270	270	240	200	170
	peak	$p_3$	[bar]	310	310	310	290	290	260	220	190
Nominal flow rate (min.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	7.06	10.59	13.64	20.45	26.67	33.33	41.67	51.67
Maximum flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	17.02	25.53	30.64	45.96	54.47	68.09	74.47	72.55
Nominal input power (max.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	2.19	3.28	4.47	6.21	8.46	8.46	9.52	9.83
Maximum input power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	6.82	10.23	12.28	17.15	20.32	22.58	20.58	17.04
Nominal Torque at $n_n$ a $p_{2n}$		$M$	[Nm]	15.47	23.20	30.94	42.97	57.30	57.30	64.46	66.61
Weight		$m$	[kg]	2.60	2.65	2.75	2.95	3.10	3.35	3.50	3.80

**Reversible motors**

Nominal Size Parameters		Sym	Unit	TM3 4	TM3 6	TM3 8	TM3 12	TM3 16	TM3 20	TM3 25	TM3 31
Actual displacement		$V_g$	[cm <sup>3</sup> ]	4.03	6.02	8.05	12.08	16.10	20.12	25.16	31.21
Rotation speed	nominal	$n_n$	[min <sup>-1</sup> ]	1500							
	minimum	$n_{min}$	[min <sup>-1</sup> ]	500							
	maximum	$n_{max}$	[min <sup>-1</sup> ]	4000	4000	3600	3600	3200	3200	2800	2200
Pressure at outlet	minimum	$p_{1min}$	[bar]	210	210	210	210	200	160	140	100
	maximum	$p_{1max}$	[bar]	-0.30							
Pressure at inlet	max. continuous	$p_{2n}$	[bar]	270	270	270	250	250	200	180	150
	maximum	$p_{2max}$	[bar]	290	290	290	270	270	240	200	170
	peak	$p_3$	[bar]	310	310	310	290	290	260	220	190
Nominal flow rate (min.) at $n_n$ and $p_{2n}$		$Q_n$	[dm <sup>3</sup> .min <sup>-1</sup> ]	7.06	10.59	13.64	20.45	26.67	33.33	41.67	51.67
Maximum flow rate at $n_{max}$ and $p_{2max}$		$Q_{max}$	[dm <sup>3</sup> .min <sup>-1</sup> ]	17.02	25.53	30.64	45.96	54.47	68.09	74.47	72.55
Nominal input power (max.) at $n_n$ and $p_{2n}$		$P_n$	[kW]	2.19	3.28	4.47	6.21	8.46	8.46	9.52	9.83
Maximum input power at $n_{max}$ and $p_{2max}$		$P_{max}$	[kW]	6.82	10.23	12.28	17.15	20.32	22.58	20.58	17.04
Nominal Torque at $n_n$ a $p_{2n}$		$M$	[Nm]	15.47	23.20	30.94	42.97	57.30	57.30	64.46	66.61
Weight		$m$	[kg]	2.60	2.65	2.75	2.95	3.10	3.35	3.50	3.80

## FORMULAS USED FOR CALCULATION

### Flow rate

$$Q = \frac{V_g \cdot n}{1000 \cdot \eta_v} \quad [\text{dm}^3 \text{min}^{-1}]$$

$V_g$  [cm<sup>3</sup>] pump displacement  
 $n$  [min<sup>-1</sup>] rotation speed  
 $\eta_v$  [-] volumetric efficiency

### Displacement

$$V_g = \frac{Q \cdot 1000 \cdot \eta_v}{n} \quad [\text{cm}^3]$$

### Torque

$$M_k = \frac{V_g \cdot p \cdot \eta_m}{20 \cdot \pi} \quad [\text{Nm}]$$

$p$  [bar] required pressure at outlet  
 $\eta_m$  [-] mechanical efficiency

### Input power

$$P = \frac{V_g \cdot n \cdot p \cdot \eta_t}{600 \cdot 1000} \quad [\text{kW}]$$

$\eta_t$  [-] total efficiency

## PUMP EFFICIENCIES

### Volumetric efficiency $\eta_v$

It determines the amount of flow losses. Its value is  $\eta_v = 0.92 \div 0.98$  (depending on rotation speed, viscosity of working liquid and outlet pressure). It can be expressed as follows:

$$\eta_v = \frac{Q_{theor}}{Q_{act.}} \quad [-]$$

$Q_{act.}$  [dm<sup>3</sup>min<sup>-1</sup>] actual flow rate  
 $Q_{theor}$  [dm<sup>3</sup>min<sup>-1</sup>] theoretical flow rate

### Mechanical efficiency $\eta_m$

It determines mechanical losses. Its value is about  $\eta_m = 0.85$ . It can be expressed as follows:

$$\eta_m = \frac{M_{act.}}{M_{theor}} \quad [-]$$

$M_{act.}$  [Nm] actual torque  
 $M_{theor}$  [Nm] theoretical torque

### Total efficiency $\eta_t$

It is defined as product of  $\eta_v$  and  $\eta_m$  and determines the difference between theoretical and actual required input power:

$$\eta_t = \eta_v \cdot \eta_m = \frac{P_{act.}}{P_{theor}} \quad [-]$$

$P_{act.}$  [kW] actual input power  
 $P_{theor}$  [kW] theoretical input power

## WORKING LIQUID

- Mineral oils for hydraulic drives
- Hydraulic liquids based on plant oils suitable for hydraulic drives

### Liquid temperature

$$t = -20 \div +80 \text{ [}^\circ\text{C]} \quad \text{when used with FKM (Viton) seal up to } 120 \text{ [}^\circ\text{C]}$$

### Cinematic viscosity

Recommended (during continuous operation):  $\nu = 20 \div 80 \cdot 10^{-6} \text{ [m}^2 \cdot \text{s}^{-1}\text{]}$

Maximum (cold starting, at viscosity  $>1000$ , operating pressure  $<10$  bar is permissible, speed  $<1500 \cdot \text{min}^{-1}$ ):  $\nu = 1200 \cdot 10^{-6} \text{ [m}^2 \cdot \text{s}^{-1}\text{]}$

Minimum (operating mode at  $10 \cdot 10^{-6}$  up to  $20 \cdot 10^{-6}$  should be consulted with manufacturer):  $\nu = 10 \cdot 10^{-6} \text{ [m}^2 \cdot \text{s}^{-1}\text{]}$

### Filtration coefficient $\beta_\alpha$

$$\beta_{25} 75 \geq \text{(for pressure } p_2 < 200 \text{ bar)}$$

$$\beta_{10} 75 \geq \text{(for pressure } p_2 > 200 \text{ bar)}$$

### Liquid contamination class according to ISO 4406

$$21/18/15 \quad \text{(for pressure } p_2 < 200 \text{ bar)}$$

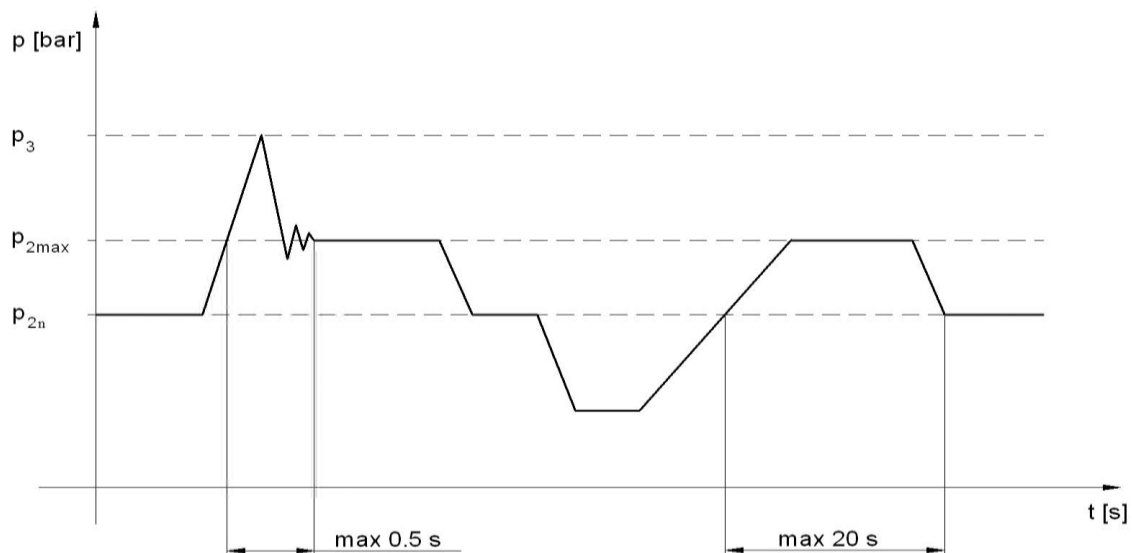
$$20/17/14 \quad \text{(for pressure } p_2 > 200 \text{ bar)}$$

### Liquid contamination class according to NAS 1638

$$10 \quad \text{(for pressure } p_2 < 200 \text{ bar)}$$

$$8 \quad \text{(for pressure } p_2 > 200 \text{ bar)}$$

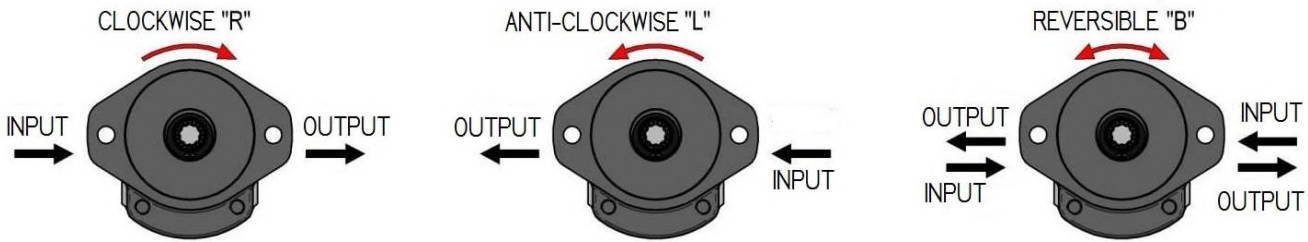
## PRESSURE LOAD



$p_{2n}$	<b>max. contin. pressure</b>	max. working pressure, at which the pump can be operated without time limitation.
$p_{2max}$	<b>max. pressure</b>	maximum pressure permissible for a short time, max. 20s.
$p_3$	<b>peak pressure</b>	short-time pressure (fractions of a second) arising in case of a sudden change of the operating mode; any excess of this pressure during operation is impermissible.

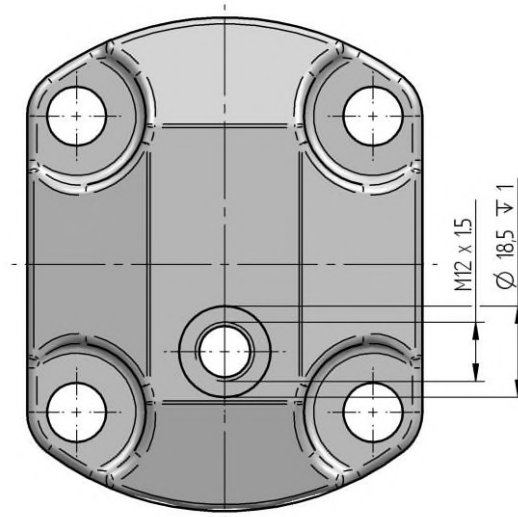
## DIRECTION OF ROTATION

Determine direction of rotation by looking at the drive shaft. The motor can only be used in the specified direction of rotation

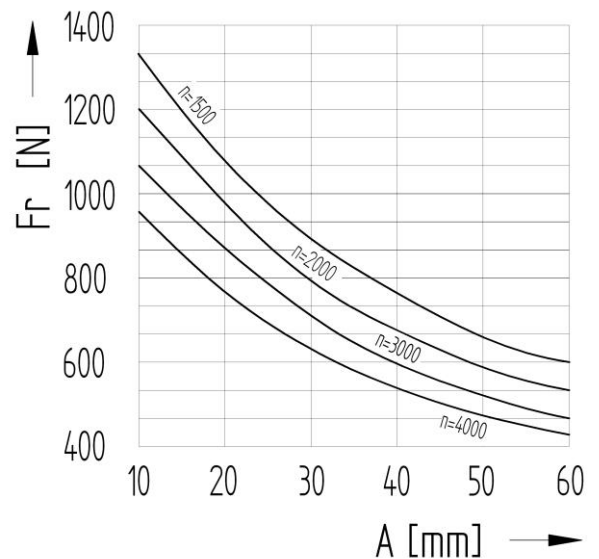
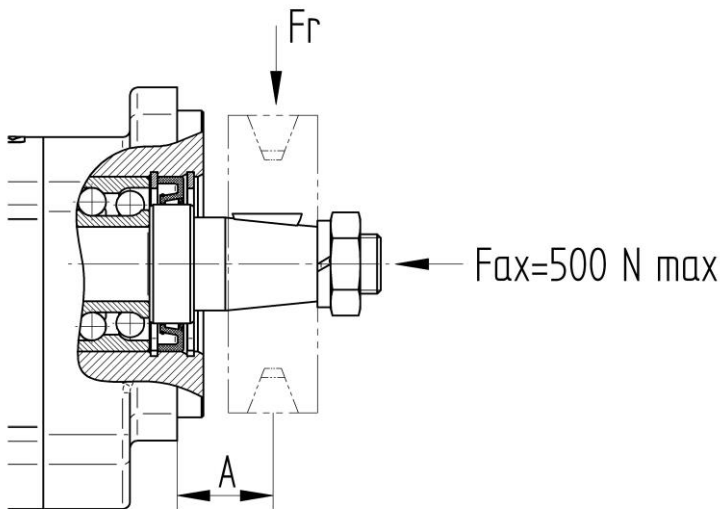


## REVERSIBLE DESIGN

The motors with the possibility of bidirectional rotation have a different internal arrangement requiring drainage. Two types are used - internal and external. The internal drainage is always interconnected with the outlet by means of valves. The external drainage is solved by an orifice located in the cover opposite the driven gear.

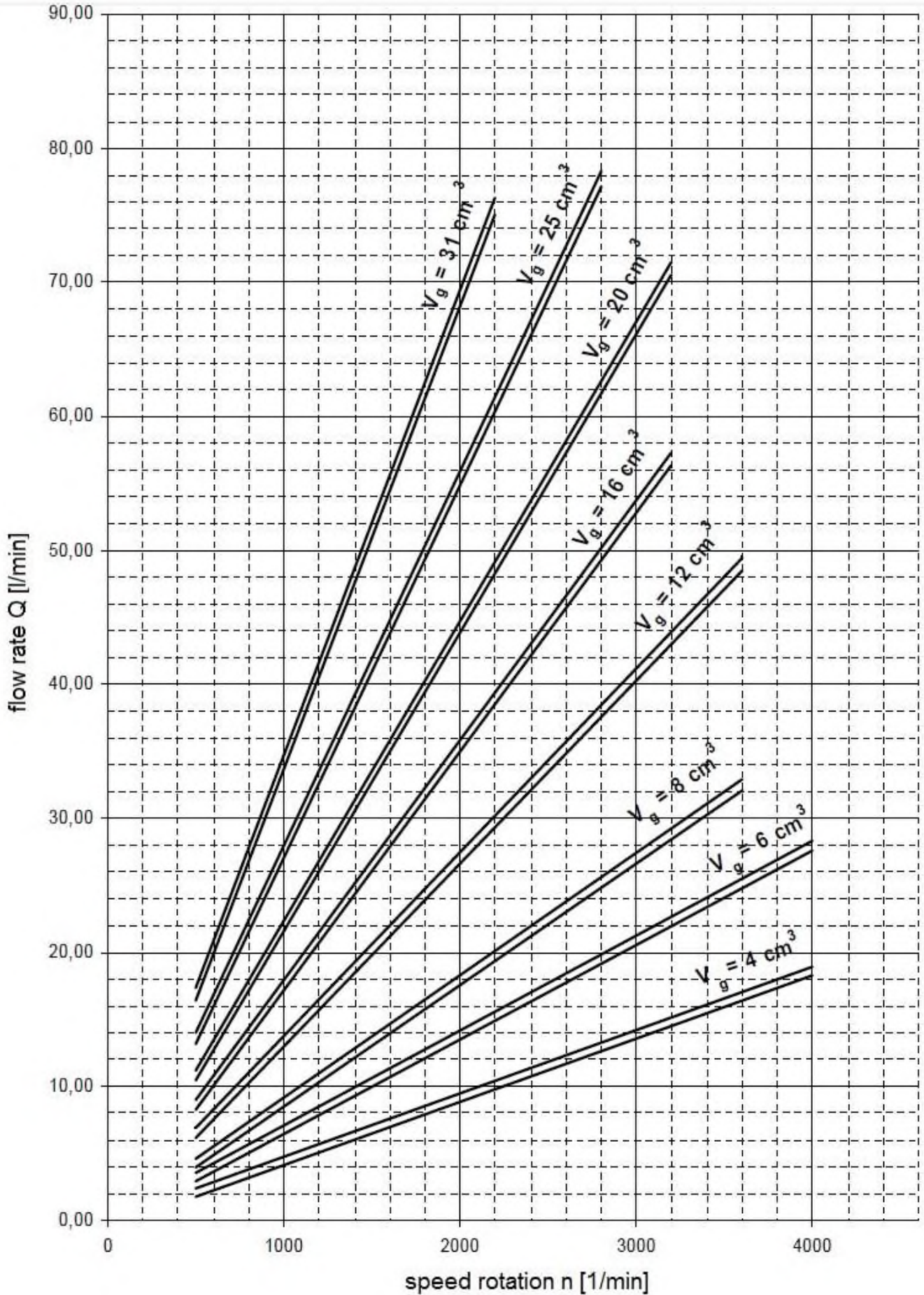


## MOTOR WITH A FRONT-END BEARING



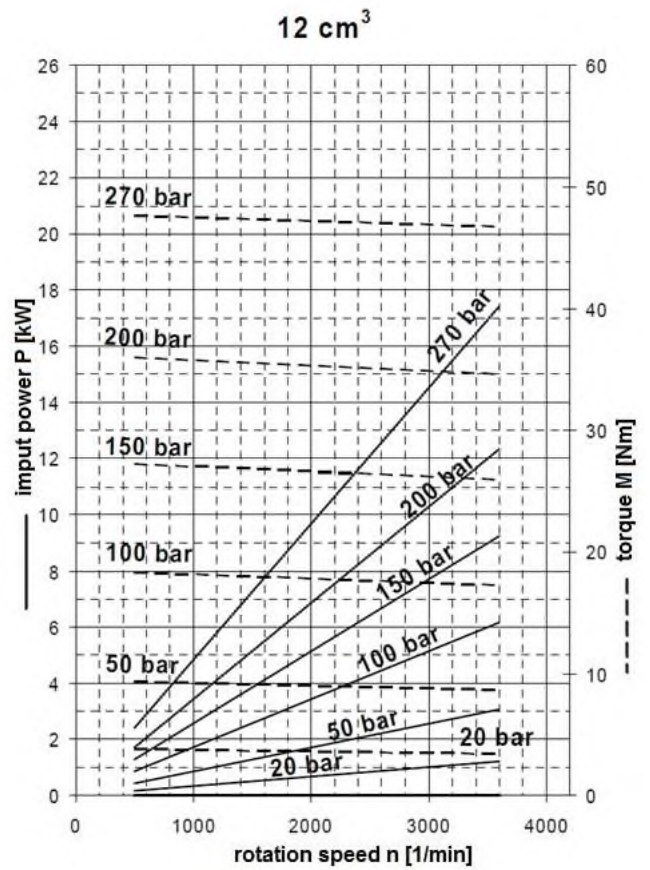
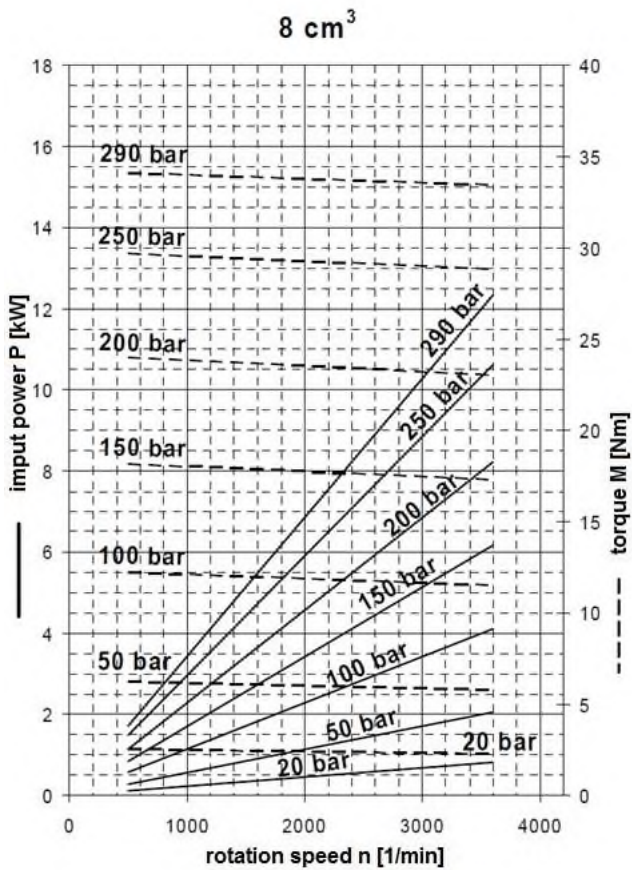
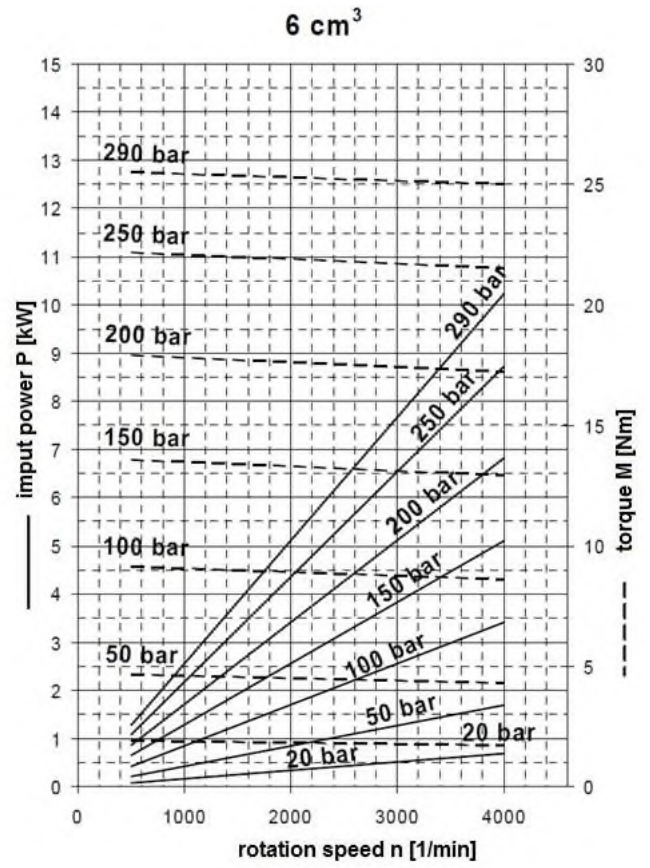
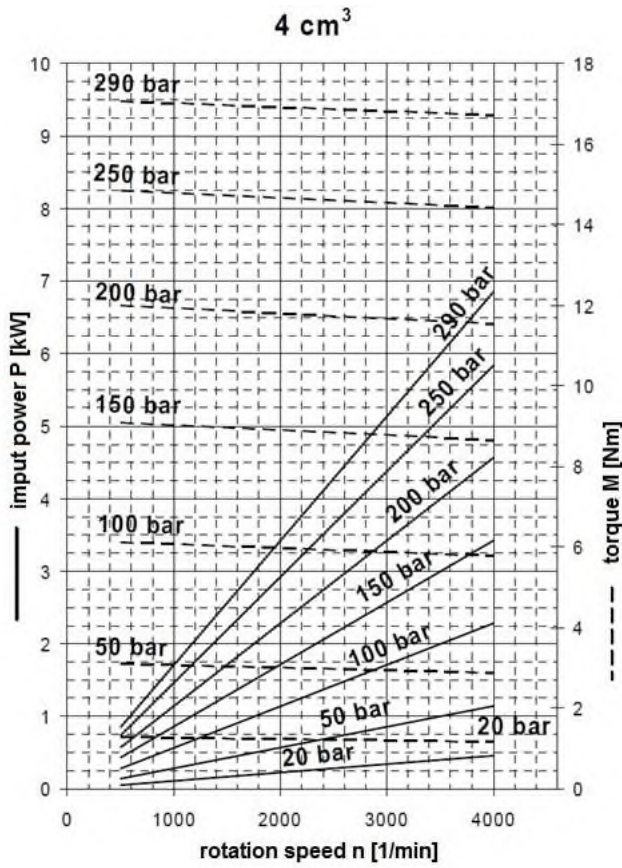
A driven device must not generate an axial or a radial load of the motor shaft, unless this is exclusively permitted for the motor with a front-end bearing.

**TM3 FLOW RATE AND POWER CURVES**

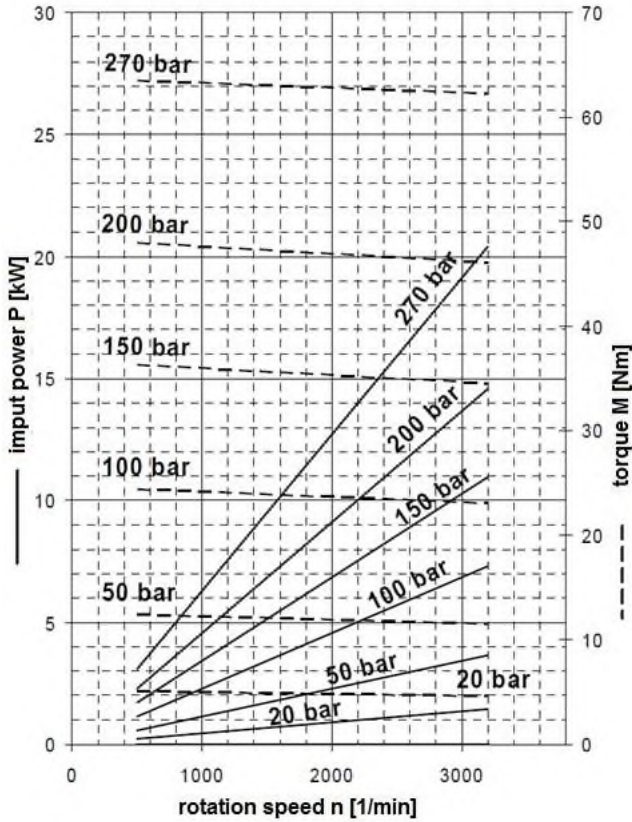


Above curves apply to ISO Vg 46 oil at temperature  $t = 45^{\circ}\text{C}$ .

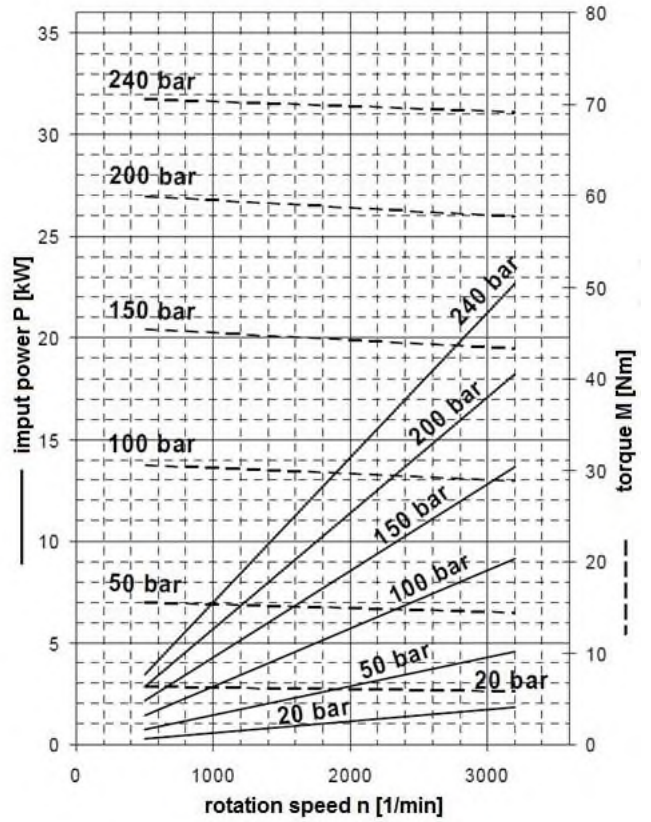




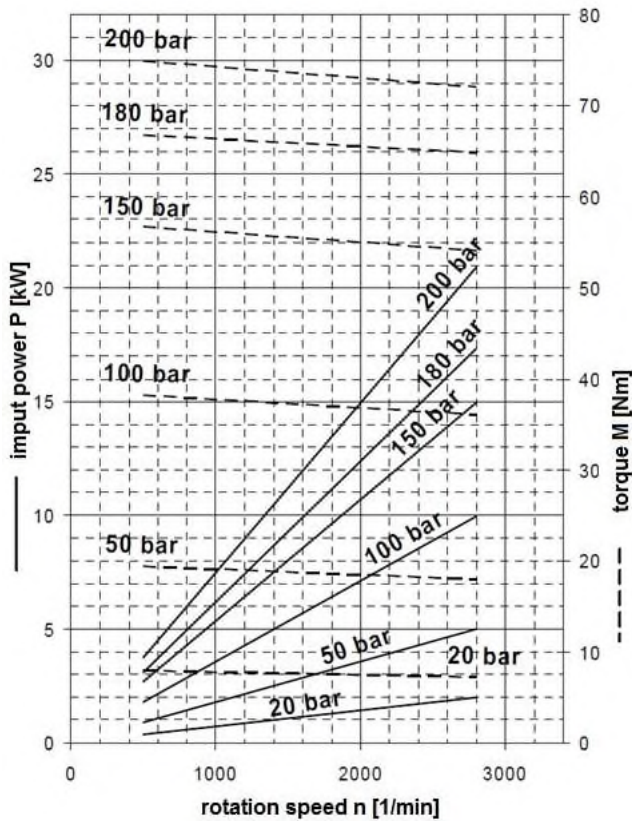
16 cm<sup>3</sup>



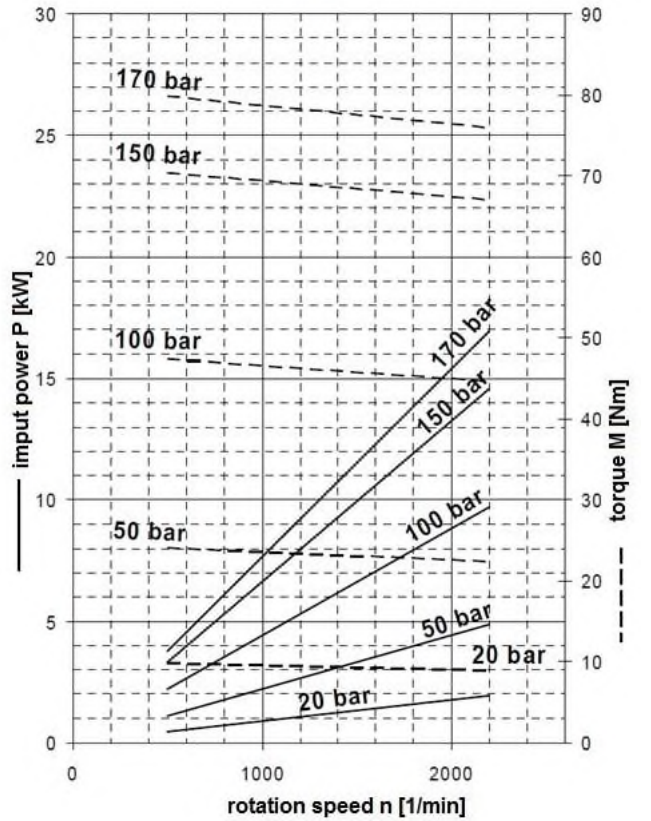
20 cm<sup>3</sup>



25 cm<sup>3</sup>



31 cm<sup>3</sup>



**ORDER KEY**

**TM3 - 16 R - S02 D04 - S G04 G03 - V . 001**

Code	Displacement [cm <sup>3</sup> ]
4	4,03
6	6,02
8	8,05
12	12,08
16	16,10
20	20,12
25	25,16
31	31,21
XX	Other displacements on request

Code	Direction of Rotation
R	Clockwise
L	Anti-clockwise
B	Bi-directional

Code	Type
TM3	TM3 Series Gear Motor

Code	Flange design
F02	Square flange, centre ring Ø 80
R05	Rectangular flange, centre ring Ø 36,5
R06	Rectangular flange, centre ring Ø 80
R07	Rectangular flange, centre ring Ø 60
S02	SAE A
S03	SAE B
A07	Flange with trough-bolts, centre ring Ø 50
A08	Flange with trough-bolts, centre ring Ø 50
A09	Flange with trough-bolts, centre ring Ø 52 with O-ring
A10	Flange with trough-bolts, centre ring Ø 52 with O-ring
Z	Special design

Code	Location of inlets and outlets
S	Side (in the body)
R	Rear (in the cover)
C	Combination
Z	Special design

Code	Drive shaft design
C07	Taper 1:8, Key width 3
C08	Taper 1:8, Key width 3,2
C09	Taper 1:8, Key width 4
C10	Taper 1:5, Key width 3
D04	Spline SAE 9T 16/32 DP
D06	Spline SAE 11T l = 32, 16/32 DP
D07	Spline SAE 11T l = 38, 16/32 DP
D08	Spline CSN 17x1,25
D09	Spline DIN 5482 B17x14
D10	Spline GOST 6033-80
D11	Spline 16x13x3,5
K07	Cross coupling
V09	Cylindric Ø5/8'', Key 4x4
V11	Cylindric Ø15, Key 4x4
V12	Cylindric Ø3/4'', Key 4,8x4,8
V13	Cylindric Ø20, Key 6x6
Z	Special design

Code	Special arrangements
-	No special arrangements
001	With front-end bearing type 1
002	With front-end bearing type 2
003	Sealed section for multiple version
004	Without shaft seal
005	Inlet in body, outlet in cover
006	Inlet in cover, outlet in body
007	Inlet in body, outlet in flange
008	Inlet in flange, outlet in body
009	Drain M12 x 1,5 in cover
010	With front-end bearing type 3
011	Drain G¼ in cover
012	Internal drain
013	Variseal
014	Shaft seal – double lip

Code	Seal material
N	NBR
V	FKM
H	HNBR

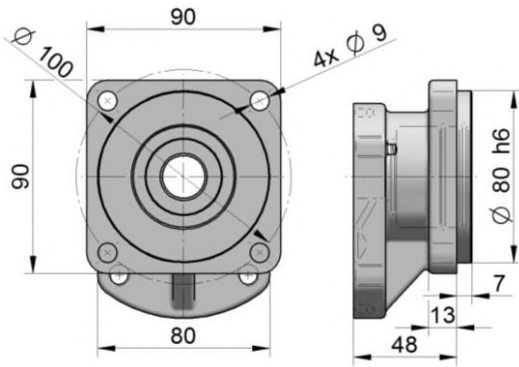
Code	Liquid inlet and outlet connection shape
M05	Thread M18x1,5
M09	Thread M27x2
G03	Thread BSP G1/2
G04	Thread BSP G3/4
G05	Thread BSP G1''
U04	Thread 7/8–14 UNF-2B
U05	Thread 1–1/16–12 UN-2B
H05	Flanged fitting Ø15, Square 4xM6 Ø35
H06	Flanged fitting Ø20, Square 4xM6 Ø40
H10	Flanged fitting Ø26, Square 4xM8 Ø55
H07	Flanged fitting Ø13,5, Square 4xM6 Ø30
H08	Flanged fitting Ø20, Square 4xM8 Ø40
K01	Flanged fitting Ø13,5, Cross 4xM6 Ø30
K02	Flanged fitting Ø20, Cross 4xM8 Ø40
K07	Flanged fitting Ø14, Cross 4xM8 Ø38
K08	Flanged fitting Ø19, Cross 4xM8 Ø38
Z	Special design

An example of designation for the TM3 clockwise motor with displacement of 16 cm<sup>3</sup>, SAE A flange; Spline SAE 9T; BSP side inlets in the body and FKM sealing, with front-end bearing **TM3-16R-S02D04-SG04G03-V.001**

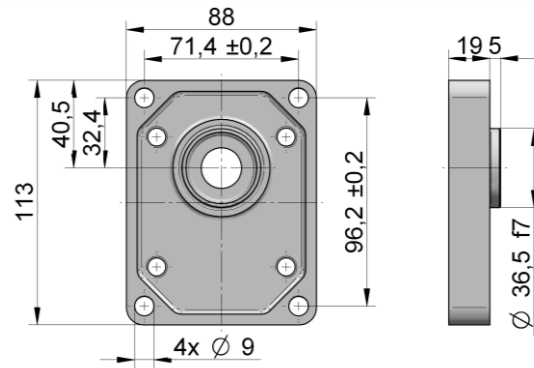


## FLANGES DESIGN

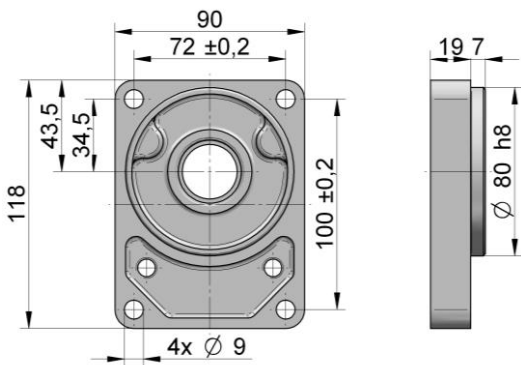
**F02:**



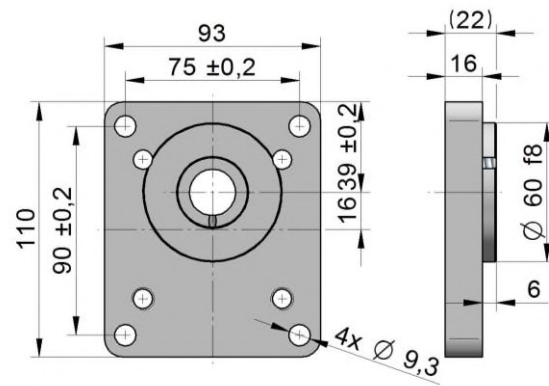
**R05:**



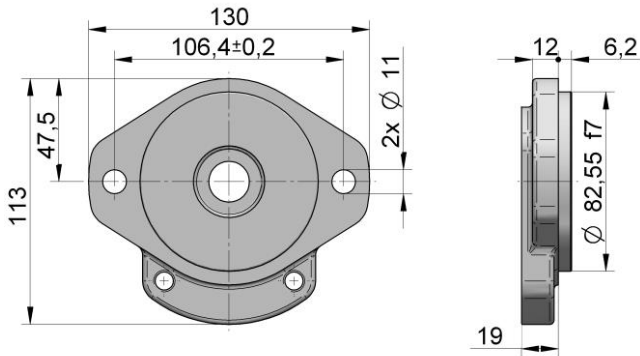
**R06:**



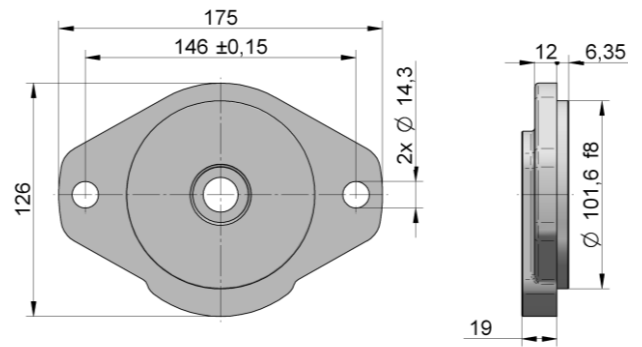
**R07:**



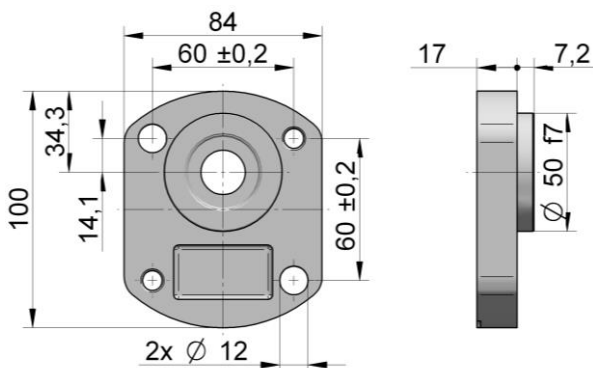
**S02:**



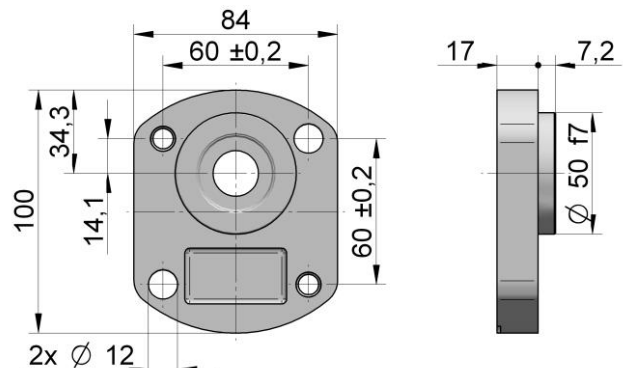
**S03:**



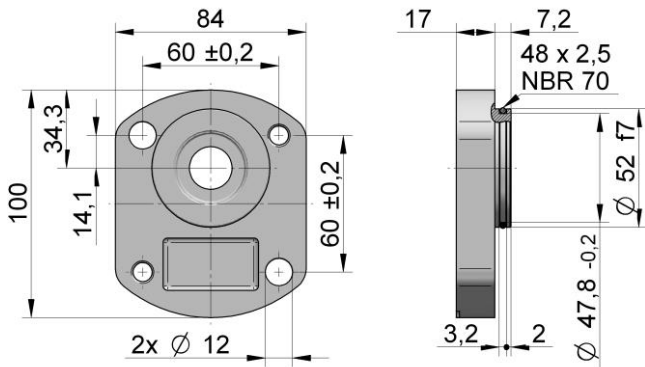
**A07:**



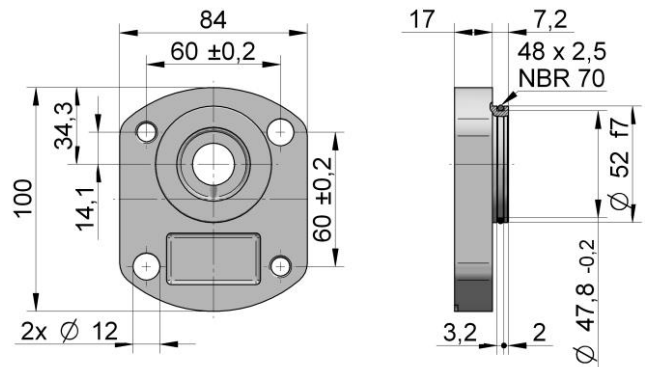
**A08:**



**A09:**



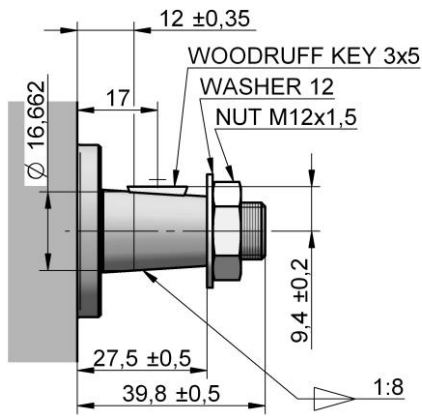
**A10:**



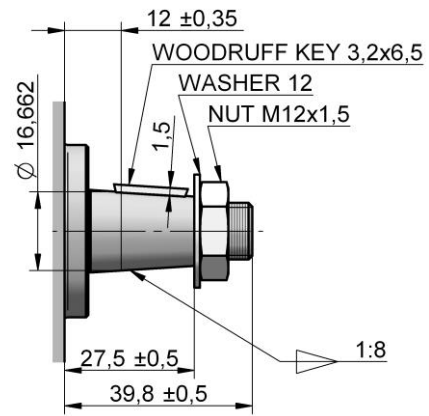
**DRIVE SHAFT**

**Note:** maximum allowed torque on a drive shaft is 100 Nm.

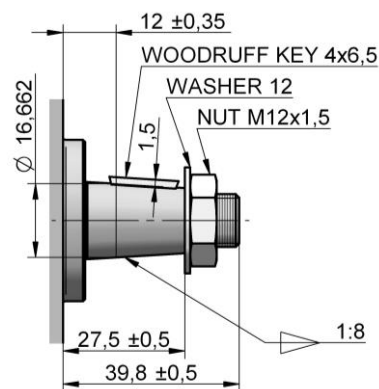
**C07:**



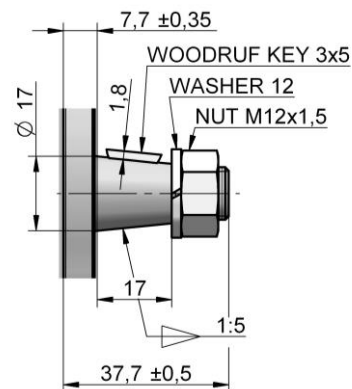
**C08:**



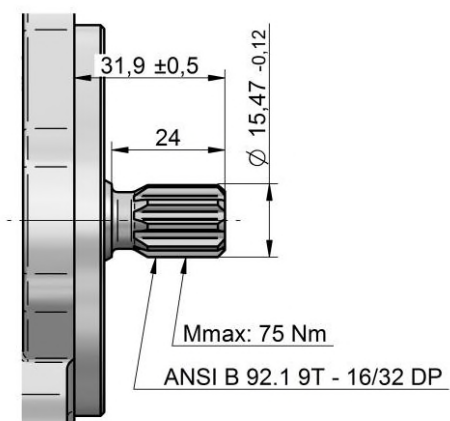
**C09:**



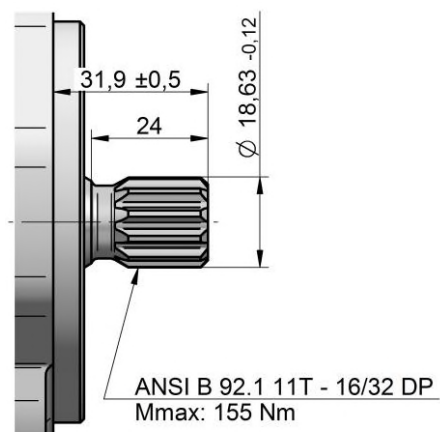
**C10:**



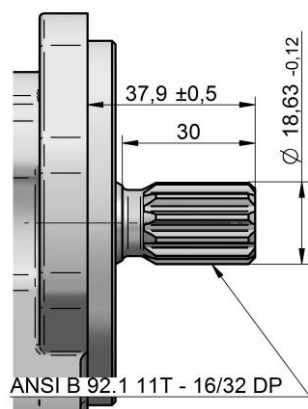
**D04:**



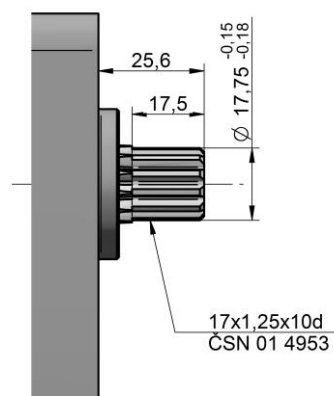
**D06:**



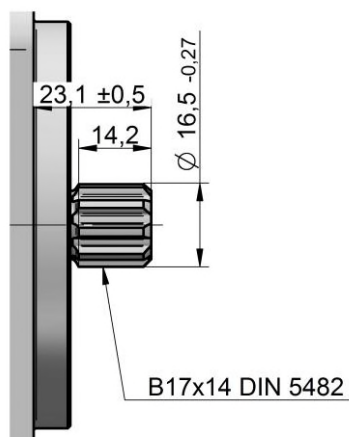
**D07:**



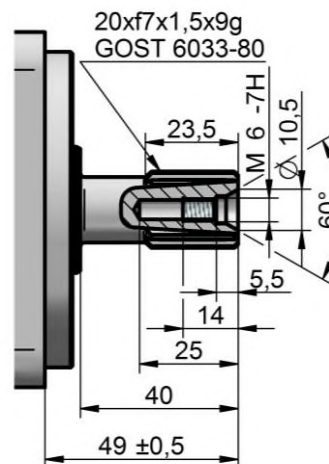
**D08:**



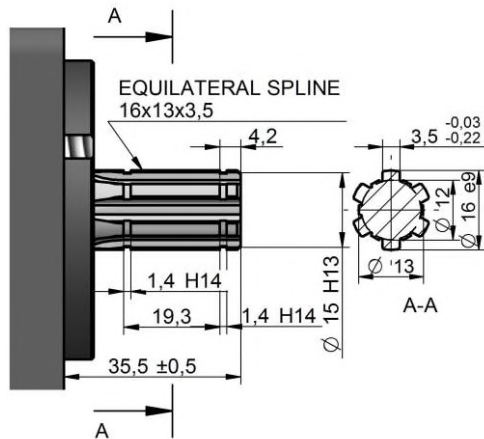
**D09:**



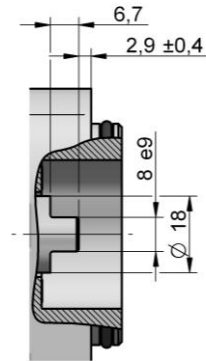
**D10:**



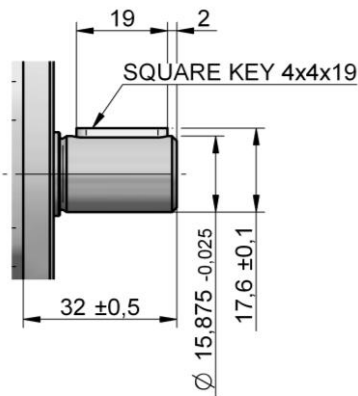
**D11:**



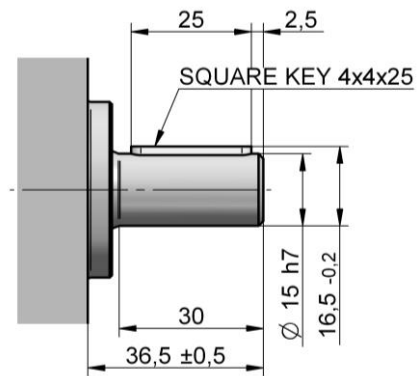
**K07**



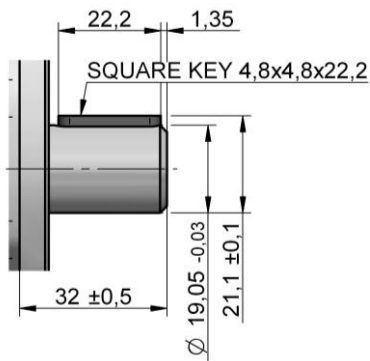
**V09:**



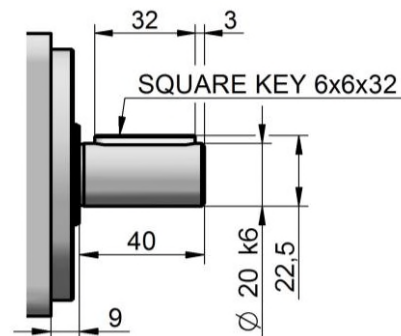
**V11:**



**V12:**



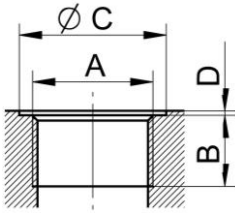
**V13:**





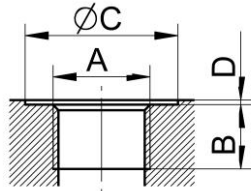
## LIQUID INLET AND OUTLET CONNECTION

### Metric thread according to ISO 6149



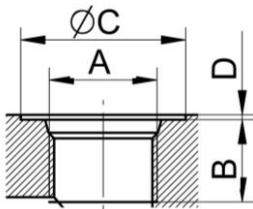
Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	A	B	C	D	Code	A	B	C	D
all	M09	M 27x2	16	33	1	M05	M18x1,5	14	24	1

### BSPP pipe thread according to ISO 228 - 1



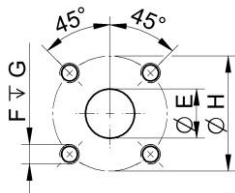
Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	A	B	C	D	Code	A	B	C	D
to 10	G03	G1/2	14	33	1	G03	G1/2	14	33	1
10 - 25	G04	G3/4	16	39						
above 25	G05	G1"	18	45						

### UNF thread according to SAE



Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	A	B	C	D	Code	A	B	C	D
to 10	U04	7/8-14 UNF-2B	17	34	1	U04	7/8-14 UNF-2B	17	34	1
11 - 31	U05	1-1/16-12 UNF-2B	19	41						

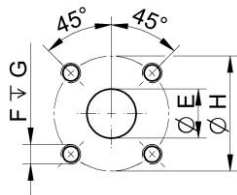
### Flanged fittings according to DIN 8901/8902



Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	E	F	G	H	Code	E	F	G	H
all	H06	20	M6	13	40	H05	15	M6	13	35
	H10	25	M8	13	55					

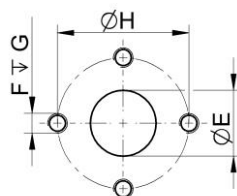
Note: H10H05 – for multiple version with one common inlet

### Flanged fittings, - „square“



Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	E	F	G	H	Code	E	F	G	H
all	H08	20	M8	13	40	H07	13,5	M6	13	30

### Flanged fittings- „cross“

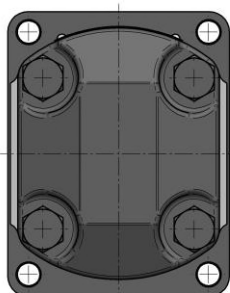
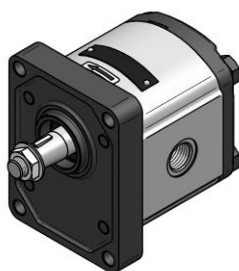
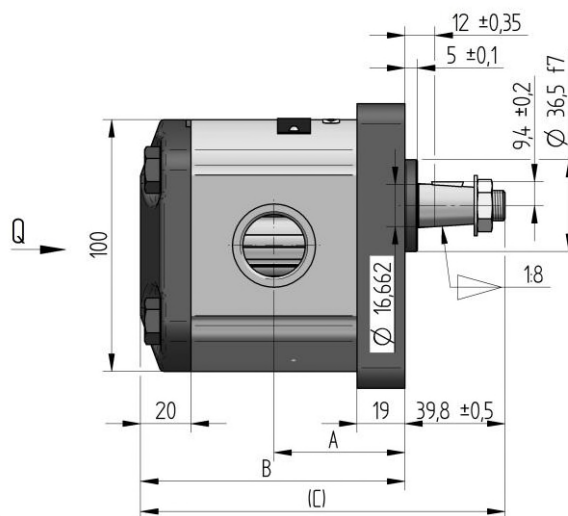
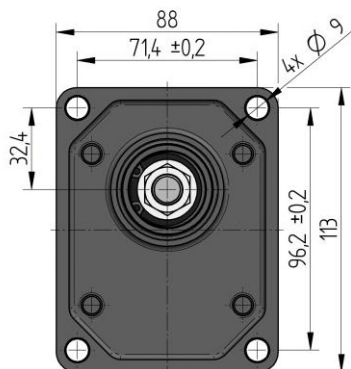


Displacement [cm <sup>3</sup> ]	Inlet					Outlet				
	Code	E	F	G	H	Code	E	F	G	H
all	K02	20	M8	13	40	K01	13,5	M6	13	30
to 10	K07	14			38	K07	14	M8		38
above 10	K08	19								

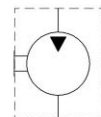
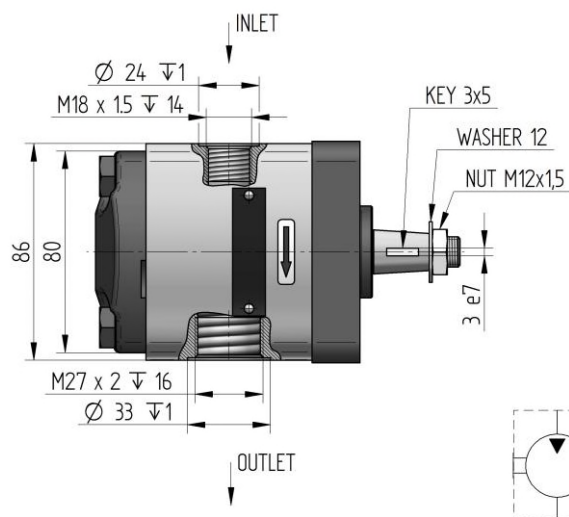
### Drains:

Displacement [cm <sup>3</sup> ]	Code	Outlet			
		A	B	C	D
all	M02	M12x1,5	12	20	1
	G01	G1/4	12	45	
	U01	7/16-20 UNF-2B	13	21	
	U02	9/16-18 UNF-2B	14	25	

## CATALOGUE SHEETS OF TM3 SERIES BASIC DESIGNS

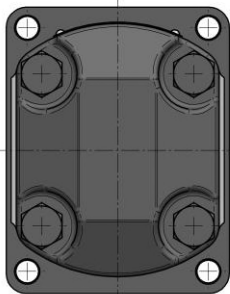
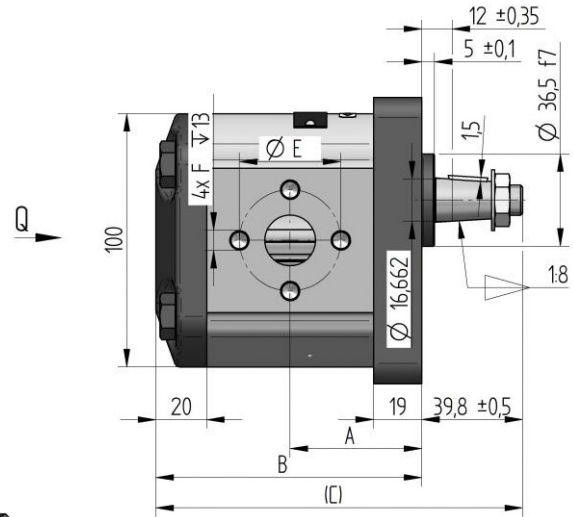
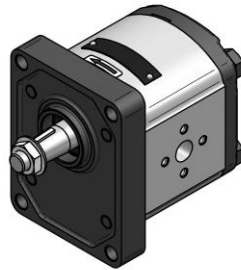
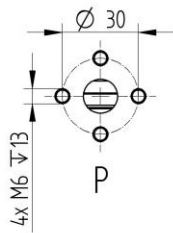
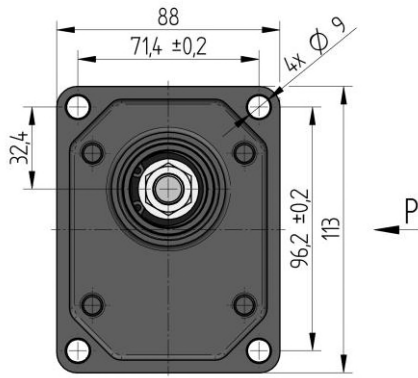


Q

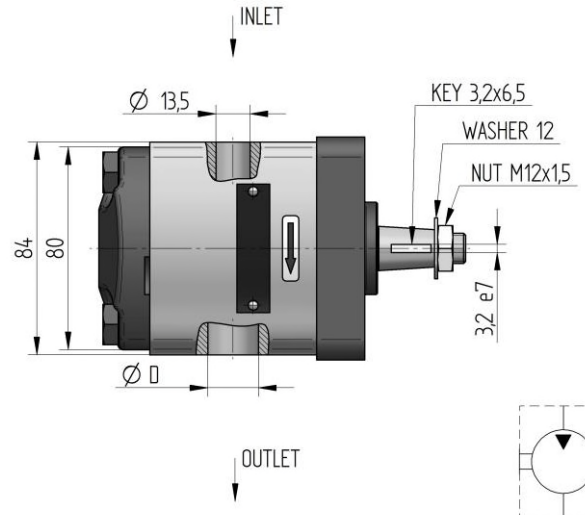


THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- R05C07-SM09M05-N		L										
TM3-31R- R05C07-SM09M05-N		R	31	150	500	2200	63.7	128.5	168.3			
TM3-25L- R05C07-SM09M05-N		L										
TM3-25R- R05C07-SM09M05-N		R	25	200	500	2800	59.0	119.1	158.9			
TM3-20L- R05C07-SM09M05-N		L										
TM3-20R- R05C07-SM09M05-N		R	20	240	500	3200	55.0	111.2	151.0			
TM3-16L- R05C07-SM09M05-N		L										
TM3-16R- R05C07-SM09M05-N		R	16	260	500	3200	51.9	104.9	144.7			
TM3-12L- R05C07-SM09M05-N		L										
TM3-12R- R05C07-SM09M05-N		R	12	260	500	3600	48.8	98.6	138.4			
TM3-8L- R05C07-SM09M05-N		L										
TM3-8R- R05C07-SM09M05-N		R	8	280	500	3600	45.6	92.3	132.1			
TM3-6L- R05C07-SM09M05-N		L										
TM3-6R- R05C07-SM09M05-N		R	6	280	500	4000	44.0	89.2	129.0			
TM3-4L- R05C07-SM09M05-N		L										
TM3-4R- R05C07-SM09M05-N		R	4	280	500	4000	42.5	86.0	125.8			
ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	DIMENSIONS [mm]		

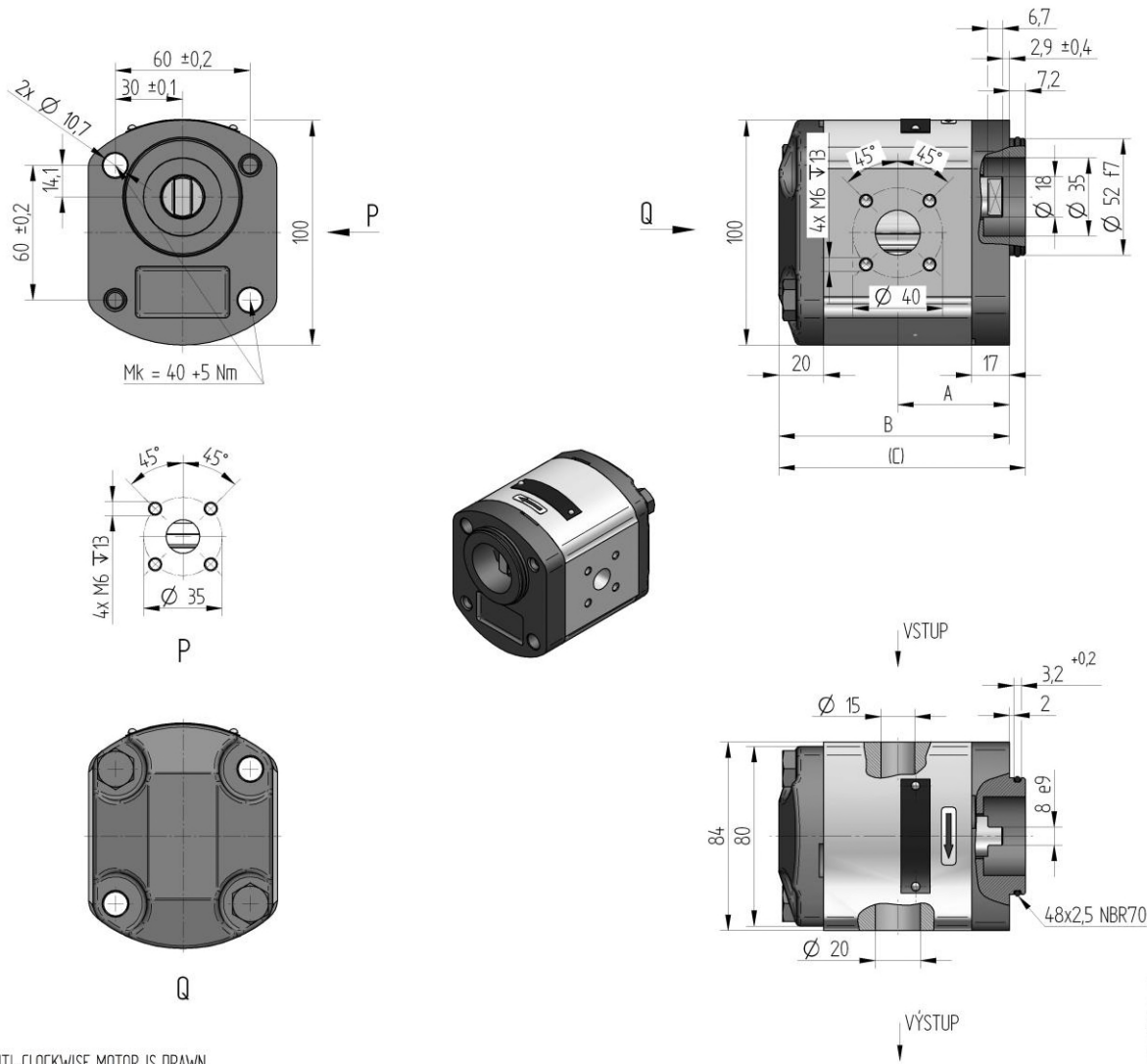


Q



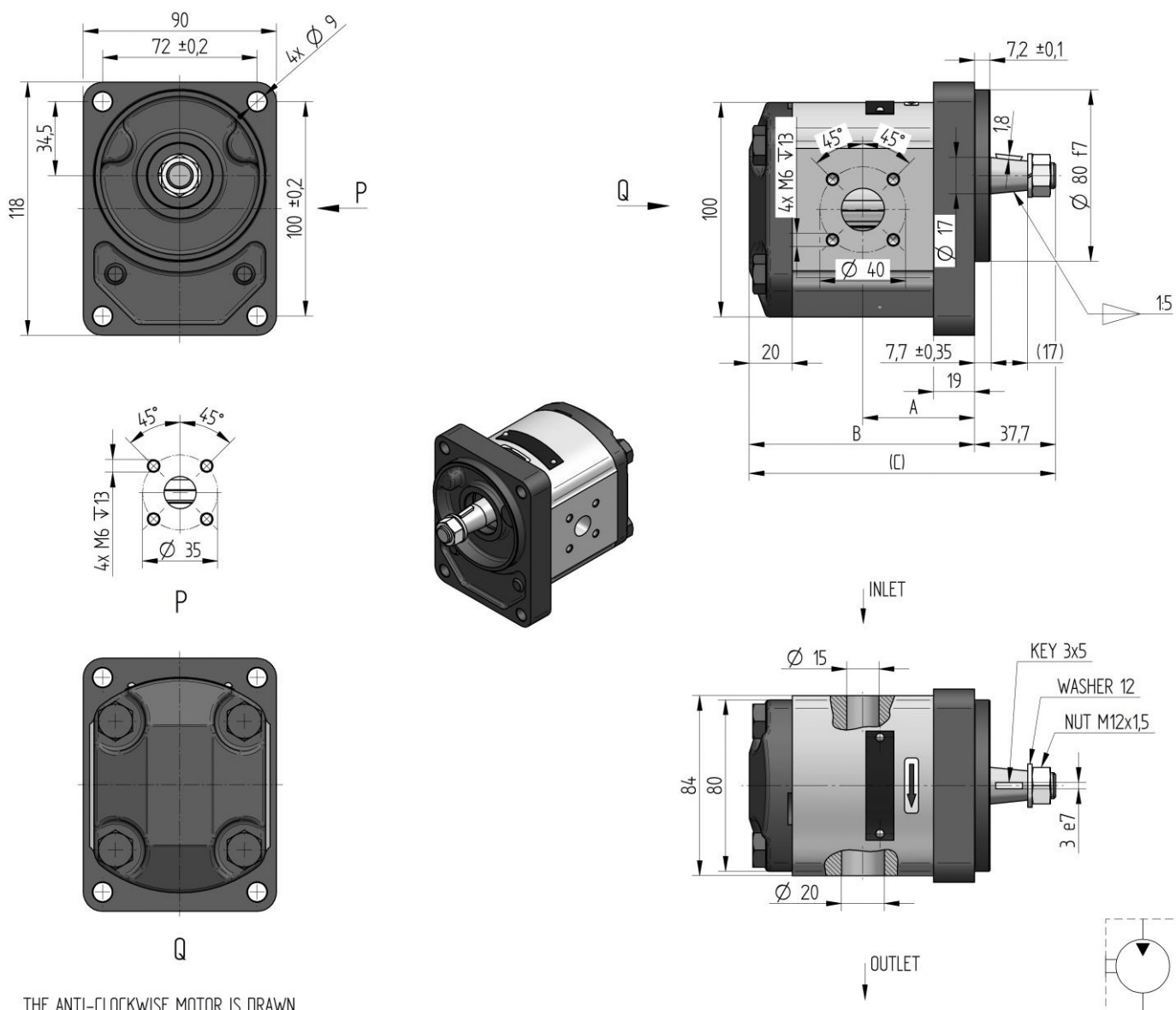
THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- R05C08-SK02K01-N		L	31	150	2200	63.7	128.5	168.3	Ø20	Ø40	M8		
TM3-31R- R05C08-SK02K01-N		R	31	150	2200	63.7	128.5	168.3	Ø20	Ø40	M8		
TM3-25L- R05C08-SK02K01-N		L	25	200	2800	59.0	119.1	158.9	Ø20	Ø40	M8		
TM3-25R- R05C08-SK02K01-N		R	25	200	2800	59.0	119.1	158.9	Ø20	Ø40	M8		
TM3-20L- R05C08-SK02K01-N		L	20	240	3200	55.0	111.2	151.0	Ø20	Ø40	M8		
TM3-20R- R05C08-SK02K01-N		R	20	240	3200	55.0	111.2	151.0	Ø20	Ø40	M8		
TM3-16L- R05C08-SK02K01-N		L	16	260	3200	51.9	104.9	144.7	Ø20	Ø40	M8		
TM3-16R- R05C08-SK02K01-N		R	16	260	3200	51.9	104.9	144.7	Ø20	Ø40	M8		
TM3-12L- R05C08-SK02K01-N		L	12	260	3600	48.8	98.6	138.4	Ø20	Ø40	M8		
TM3-12R- R05C08-SK02K01-N		R	12	260	3600	48.8	98.6	138.4	Ø20	Ø40	M8		
TM3-8L- R05C08-SK01K01-N		L	8	280	3600	45.6	92.3	132.1	Ø13.5	Ø30	M6		
TM3-8R- R05C08-SK01K01-N		R	8	280	3600	45.6	92.3	132.1	Ø13.5	Ø30	M6		
TM3-6L- R05C08-SK01K01-N		L	6	280	4000	44.0	89.2	129.0	Ø13.5	Ø30	M6		
TM3-6R- R05C08-SK01K01-N		R	6	280	4000	44.0	89.2	129.0	Ø13.5	Ø30	M6		
TM3-4L- R05C08-SK01K01-N		L	4	280	4000	42.5	86.0	125.8	Ø13.5	Ø30	M6		
TM3-4R- R05C08-SK01K01-N		R	4	280	4000	42.5	86.0	125.8	Ø13.5	Ø30	M6		
ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	D	E	DIMENSIONS [mm]	



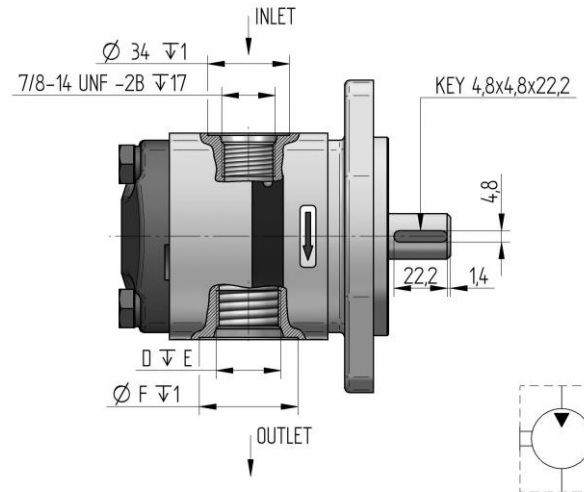
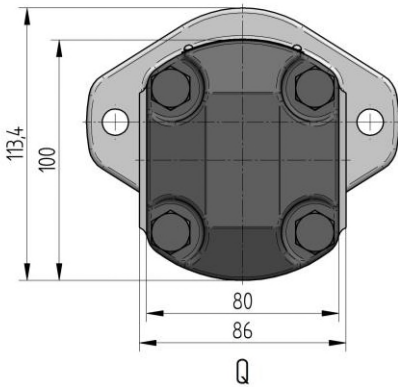
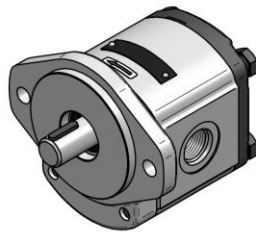
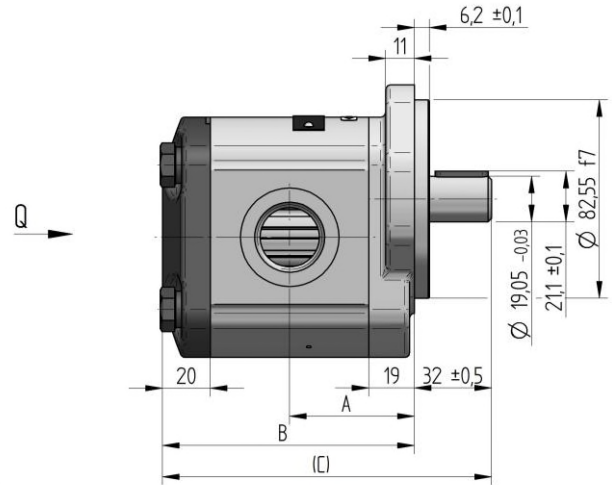
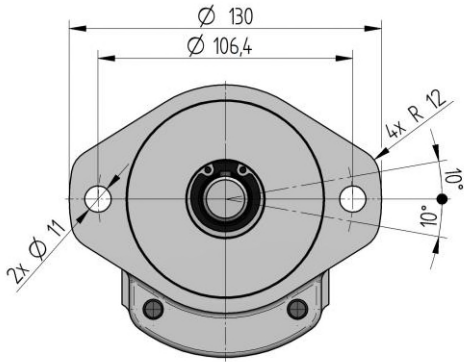
THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- A09K07-SH06H05-N.004		L	31	150	500	2200	61.7	126.5	133.7				
TM3-31R- A09K07-SH06H05-N.004		R											
TM3-25L- A09K07-SH06H05-N.004		L	25	200	500	2800	57.0	117.1	124.3				
TM3-25R- A09K07-SH06H05-N.004		R											
TM3-20L- A09K07-SH06H05-N.004		L	20	240	500	3200	53.0	109.2	116.4				
TM3-20R- A09K07-SH06H05-N.004		R											
TM3-16L- A09K07-SH06H05-N.004		L	16	260	500	3200	49.9	102.9	110.1				
TM3-16R- A09K07-SH06H05-N.004		R											
TM3-12L- A09K07-SH06H05-N.004		L	12	260	500	3600	46.8	96.6	103.8				
TM3-12R- A09K07-SH06H05-N.004		R											
TM3-8L- A09K07-SH06H05-N.004		L	8	280	500	3600	43.6	90.3	97.5				
TM3-8R- A09K07-SH06H05-N.004		R											
TM3-6L- A09K07-SH06H05-N.004		L	6	280	500	4000	42.0	87.2	94.4				
TM3-6R- A09K07-SH06H05-N.004		R											
TM3-4L- A09K07-SH06H05-N.004		L	4	280	500	4000	40.5	84.0	91.2				
TM3-4R- A09K07-SH06H05-N.004		R											
ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	DIMENSIONS [mm]			



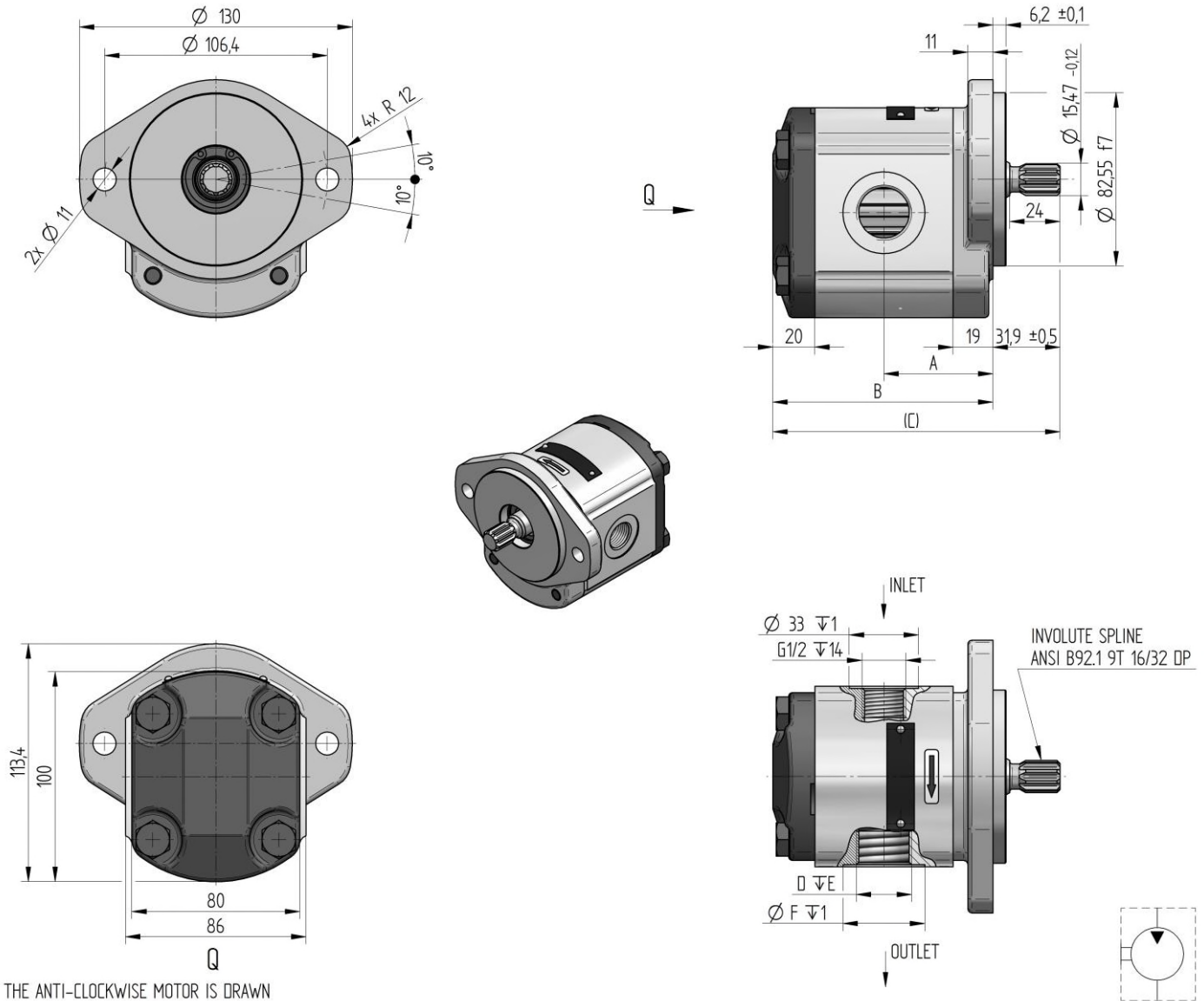
THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- R06C10-SH06H05-N		L	31	150	500	2200	63.7	128.5	168.3				
TM3-31R- R06C10-SH06H05-N		R											
TM3-25L- R06C10-SH06H05-N		L	25	200	500	2800	59.0	119.1	158.9				
TM3-25R- R06C10-SH06H05-N		R											
TM3-20L- R06C10-SH06H05-N		L	20	240	500	3200	55.0	111.2	151.0				
TM3-20R- R06C10-SH06H05-N		R											
TM3-16L- R06C10-SH06H05-N		L	16	260	500	3200	51.9	104.9	144.7				
TM3-16R- R06C10-SH06H05-N		R											
TM3-12L- R06C10-SH06H05-N		L	12	260	500	3600	48.8	98.6	138.4				
TM3-12R- R06C10-SH06H05-N		R											
TM3-8L- R06C10-SH06H05-N		L	8	280	500	3600	45.6	92.3	132.1				
TM3-8R- R06C10-SH06H05-N		R											
TM3-6L- R06C10-SH06H05-N		L	6	280	500	4000	44.0	89.2	129.0				
TM3-6R- R06C10-SH06H05-N		R											
TM3-4L- R06C10-SH06H05-N		L	4	280	500	4000	42.5	86.0	125.8				
TM3-4R- R06C10-SH06H05-N		R											
ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	DIMENSIONS [mm]			



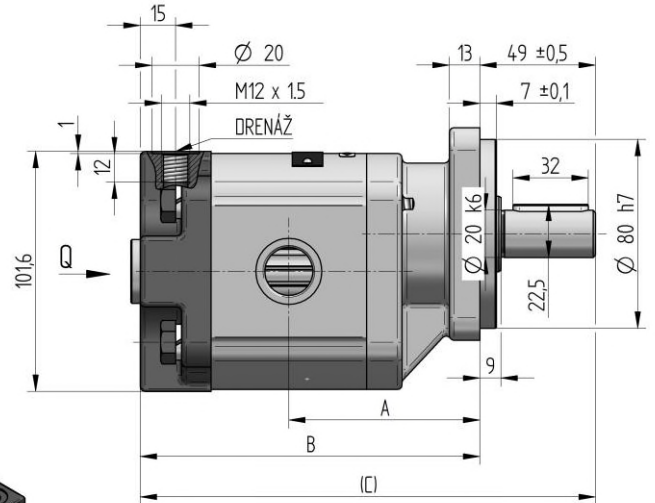
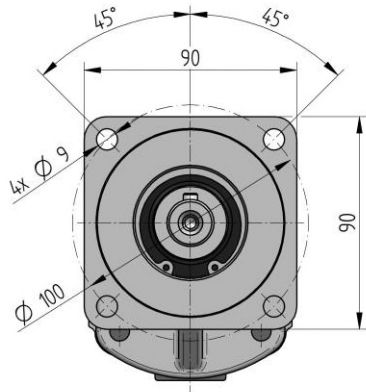
THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- S02V12-SU05U04-N		L	31	150	500	2200	63.7	128.5	160.5	1-1/16-12 UN-2B	19	41		
TM3-31R- S02V12-SU05U04-N		R	31	150	500	2200	63.7	128.5	160.5	1-1/16-12 UN-2B	19	41		
TM3-25L- S02V12-SU05U04-N		L	25	200	500	2800	59.0	119.1	151.1	1-1/16-12 UN-2B	19	41		
TM3-25R- S02V12-SU05U04-N		R	25	200	500	2800	59.0	119.1	151.1	1-1/16-12 UN-2B	19	41		
TM3-20L- S02V12-SU05U04-N		L	20	240	500	3200	55.0	111.2	143.2	1-1/16-12 UN-2B	19	41		
TM3-20R- S02V12-SU05U04-N		R	20	240	500	3200	55.0	111.2	143.2	1-1/16-12 UN-2B	19	41		
TM3-16L- S02V12-SU05U04-N		L	16	260	500	3200	51.9	104.9	136.9	1-1/16-12 UN-2B	19	41		
TM3-16R- S02V12-SU05U04-N		R	16	260	500	3200	51.9	104.9	136.9	1-1/16-12 UN-2B	19	41		
TM3-12L- S02V12-SU05U04-N		L	12	260	500	3600	48.8	98.6	130.6	1-1/16-12 UN-2B	19	41		
TM3-12R- S02V12-SU05U04-N		R	12	260	500	3600	48.8	98.6	130.6	1-1/16-12 UN-2B	19	41		
TM3-8L- S02V12-SU04U04-N		L	8	280	500	3600	45.6	92.3	124.3	7/8-14 UNF-2B	17	34		
TM3-8R- S02V12-SU04U04-N		R	8	280	500	3600	45.6	92.3	124.3	7/8-14 UNF-2B	17	34		
TM3-6L- S02V12-SU04U04-N		L	6	280	500	4000	44.0	89.2	121.2	7/8-14 UNF-2B	17	34		
TM3-6R- S02V12-SU04U04-N		R	6	280	500	4000	44.0	89.2	121.2	7/8-14 UNF-2B	17	34		
TM3-4L- S02V12-SU04U04-N		L	4	280	500	4000	42.5	86.0	118.0	7/8-14 UNF-2B	17	34		
TM3-4R- S02V12-SU04U04-N		R	4	280	500	4000	42.5	86.0	118.0	7/8-14 UNF-2B	17	34		
ORDER KEY	PURCH CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	D DIMENSIONS [mm]			E	F

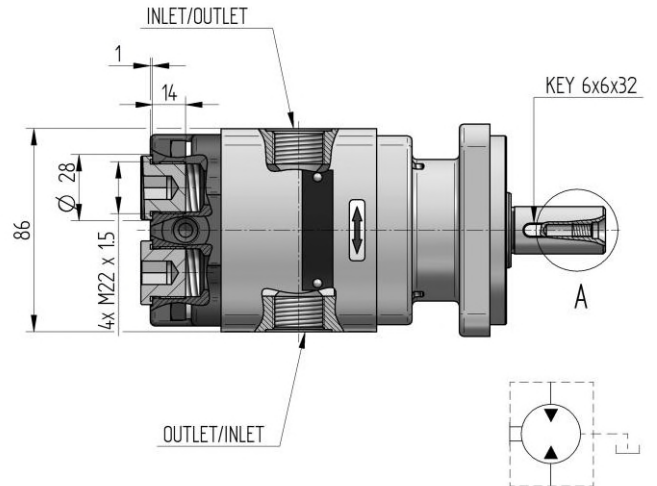
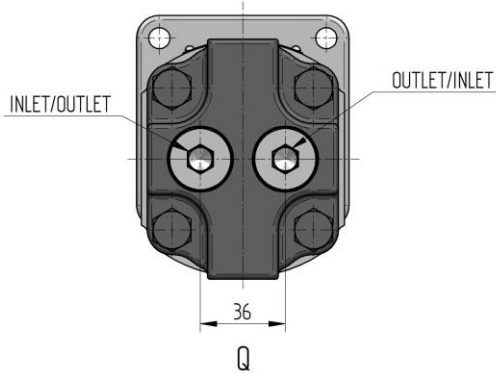
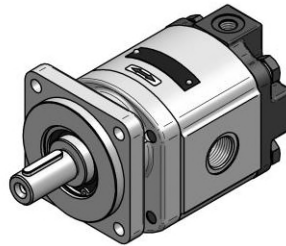
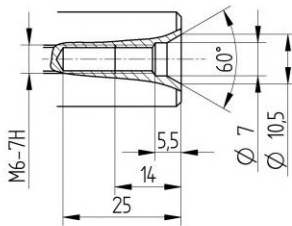


THE ANTI-CLOCKWISE MOTOR IS DRAWN

TM3-31L- S02D04-SG04G03-N		L	31	150	500	2200	63.7	128.5	160.6	G3/4	16	39
TM3-31R- S02D04-SG04G03-N		R										
TM3-25L- S02D04-SG04G03-N		L	25	200	500	2800	59.0	119.1	151.2	G3/4	16	39
TM3-25R- S02D04-SG04G03-N		R										
TM3-20L- S02D04-SG04G03-N		L	20	240	500	3200	55.0	111.2	143.3	G3/4	16	39
TM3-20R- S02D04-SG04G03-N		R										
TM3-16L- S02D04-SG04G03-N		L	16	260	500	3200	51.9	104.9	137.0	G3/4	16	39
TM3-16R- S02D04-SG04G03-N		R										
TM3-12L- S02D04-SG03G03-N		L	12	260	500	3600	48.8	98.6	130.7	G3/4	16	39
TM3-12R- S02D04-SG04G03-N		R										
TM3-8L- S02D04-SG03G03-N		L	8	280	500	3600	45.6	92.3	124.4	G1/2	14	33
TM3-8R- S02D04-SG03G03-N		R										
TM3-6L- S02D04-SG03G03-N		L	6	280	500	4000	44.0	89.2	121.3	G1/2	14	33
TM3-6R- S02D04-SG03G03-N		R										
TM3-4L- S02D04-SG03G03-N		L	4	280	500	4000	42.5	86.0	118.1	G1/2	14	33
TM3-4R- S02D04-SG03G03-N		R										
ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	D	E	F
											DIMENSIONS [mm]	



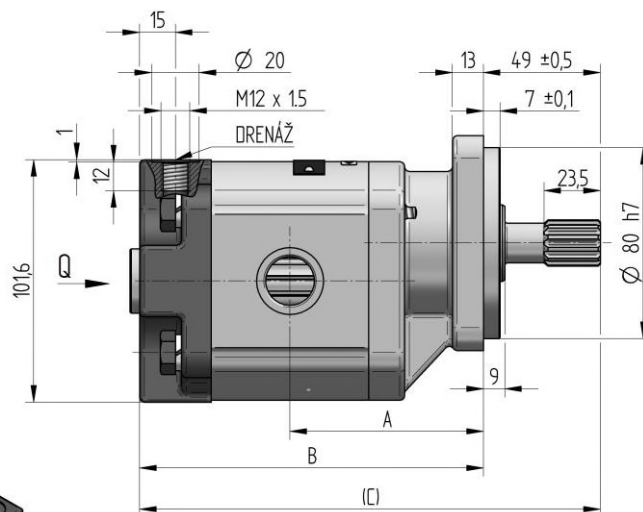
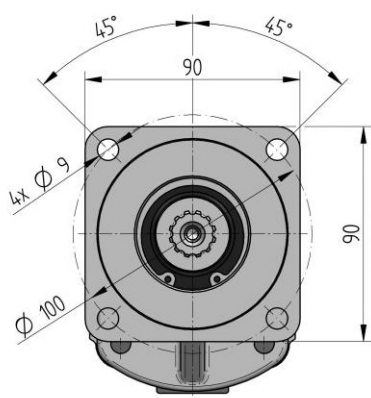
DETAIL A



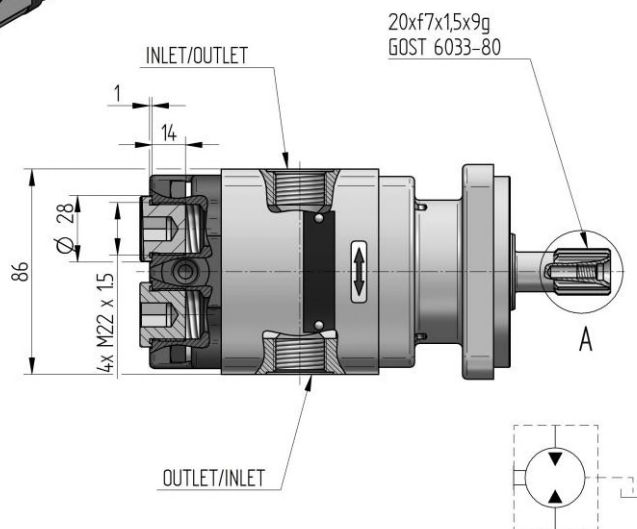
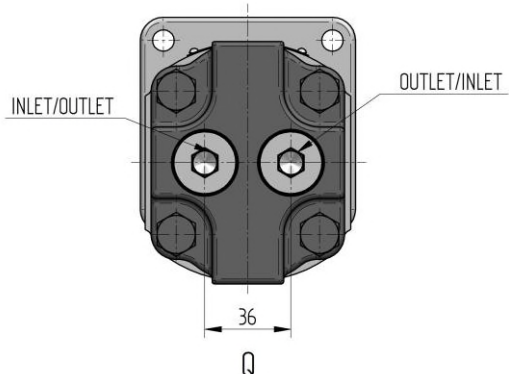
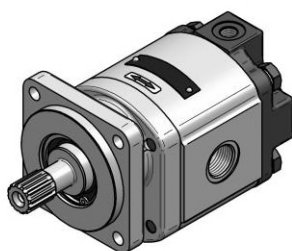
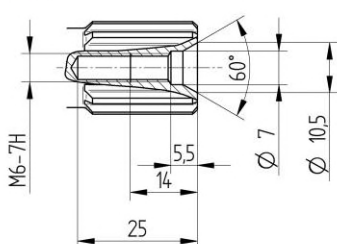
THE REVERSIBLE MOTOR IS DRAWN

ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	DIMENSIONS [mm]
		B								
		B								
		B								
		B								
		B								
		B								
TM3-13B-F02D10-CM07M07-N.027	184 9217	B	13	260	300	3500	78.6	139.1	188.1	
		B								





DETAIL A



THE REVERSIBLE MOTOR IS DRAWN

ORDER KEY	PURCH. CODE	DIRECT. OF ROT.	DISPLACEMENT [cm <sup>3</sup> /1]	NOM. PRES. [bar]	MIN. SPEED [min <sup>-1</sup> ]	MAX. SPEED [min <sup>-1</sup> ]	A	B	C	DIMENSIONS [mm]		
		B										
		B										
		B										
		B										
		B										
		B										
TM3-13B-F02V13-CM07M07-N.027	184 9215	B	13	260	300	3500	78.6	139.1	188.1			
		B										







**jihostroj**  
AERO TECHNOLOGY & HYDRAULICS

**JIHOSTROJ a.s.**  
Budějovická 148  
CZ 382 32 Velešín  
Czech Republic  
tel.: +420 380 340 511  
fax: +420 380 340 612  
e-mail: mailbox@jihostroj.cz  
http: //www.jihostroj.com

GPS 48°49'51.748" N 14°27'40.770" E

